

CSE 332  
INTRODUCTION TO VISUALIZATION  
SCIENTIFIC VISUALIZATION

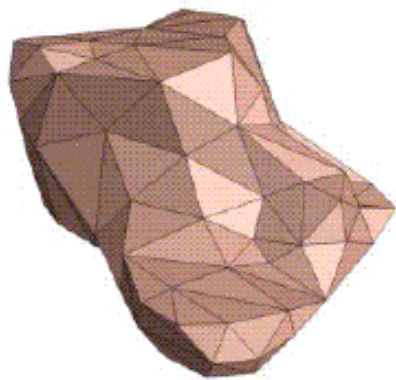
**KLAUS MUELLER**

COMPUTER SCIENCE DEPARTMENT  
STONY BROOK UNIVERSITY

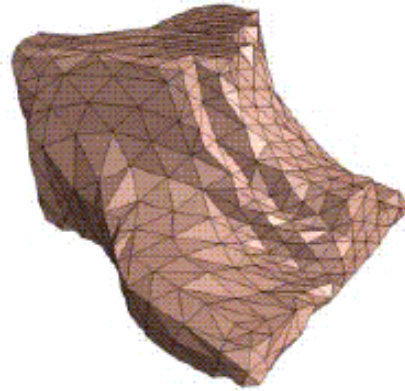
| Lecture | Topic   | Projects                     |
|---------|---|------------------------------|
| 1       | Intro, schedule, and logistics                          |                              |
| 2       | Applications of visual analytics, data, and basic tasks |                              |
| 3       | Data preparation and reduction                          | Project 1 out                |
| 4       | Data preparation and reduction                          |                              |
| 5       | Data reduction and similarity metrics                   |                              |
| 6       | Dimension reduction                                     |                              |
| 7       | Introduction to D3                                      | Project 2 out                |
| 8       | Bias in visualization                                   |                              |
| 9       | Perception and cognition                                |                              |
| 10      | Visual design and aesthetics                            |                              |
| 11      | Cluster and pattern analysis                            |                              |
| 12      | High-Dimensional data visualization: linear methods     |                              |
| 13      | High-D data vis.: non-linear methods                    | Project 3 out                |
| 14      | High-D data vis.: categorical data                      |                              |
| 15      | Principles of interaction                               |                              |
| 16      | Visual analytics and the visual sense making process    |                              |
| 17      | VA design and evaluation                                |                              |
| 18      | Visualization of graphs and hierarchies                 | Project 4 out                |
| 19      | Midterm   |                              |
| 20      | Visualization of time-varying and time-series data      |                              |
| 21      | Maps and geo-vis  |                              |
| 22      | Computer graphics and volume rendering                  |                              |
| 23      | Techniques to visualize spatial (3D) data               | Project 4 halfway report due |
| 24      | Scientific and medical visualization                    |                              |
| 25      | Non-photorealistic rendering                            |                              |
| 26      | Memorable visualizations, visual embellishments         | Project 5 out                |
| 27      | Infographics design                                     |                              |
| 28      | Projects Hall of Fame demos                             |                              |

# Rendering Volumes as Surfaces

- Objects are explicitly defined by a surface or boundary representation (explicit inside vs outside)
- This boundary representation can be given by:
  - a mesh of polygons:



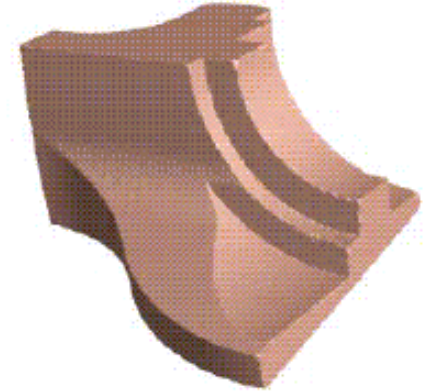
200 polys



1,000 polys



15,000 polys



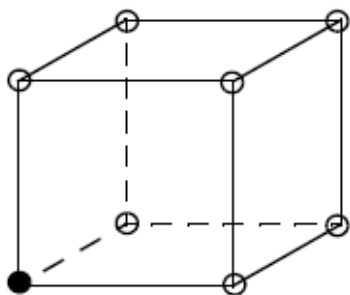
- a mesh of spline patches:



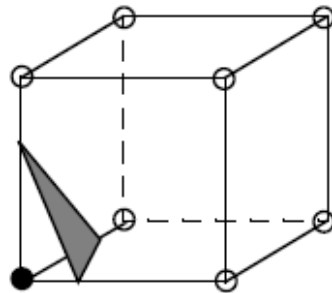
an "empty" foot

# The Marching Cubes Polygonization Algorithm

- The *Marching Cubes (MC)* algorithm converts a volume into a polygonal model
  - this model *approximates* a chosen iso-surface by a mesh of polygons
  - the polygonal model can then be rendered, for example, using a fast z-buffer algorithm
  - if another iso-surface is desired, then MC has to be run again
- Steps:
  - imagine all voxels above the iso-value are set to 1, all others are set to 0
  - the goal is to find a polygonal surface that includes all 1-voxels and excludes all 0-voxels
  - look at one volume cell (a cube) at a time → hence the term *Marching Cubes*
  - here are 2 of 256 possible configurations:

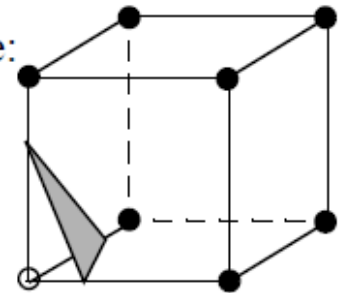


only 1 voxel > iso-value



the polygon that separates  
inside from outside

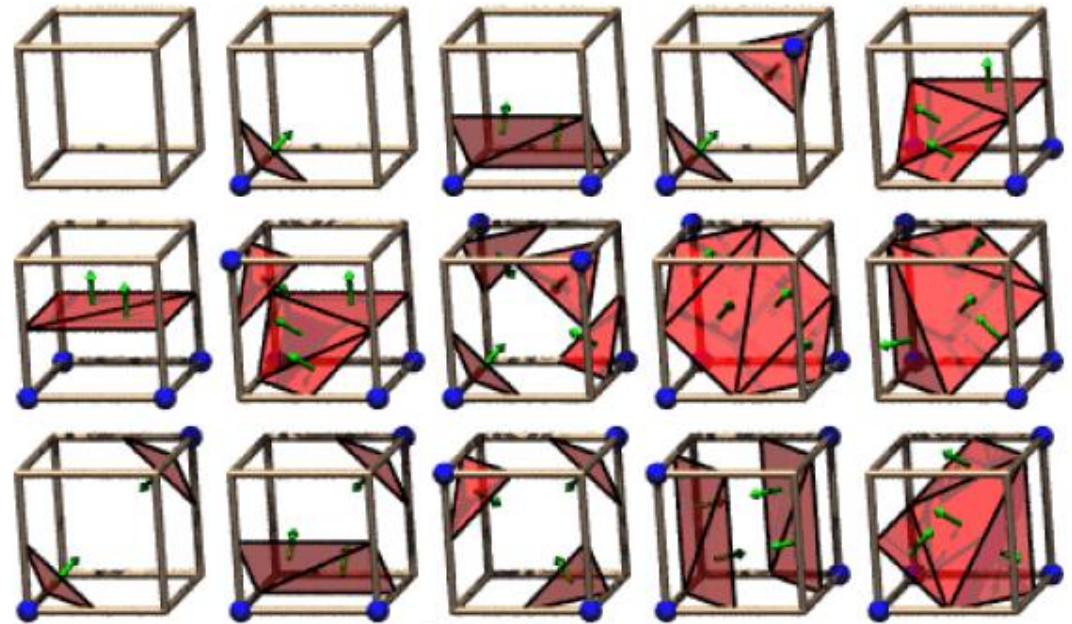
the reverse case:



7 voxels > iso-value  
the same polygon results

## Marching Cubes (2)

- One can identify 15 base cases
  - Use symmetry and reverses to get the other 241 cases

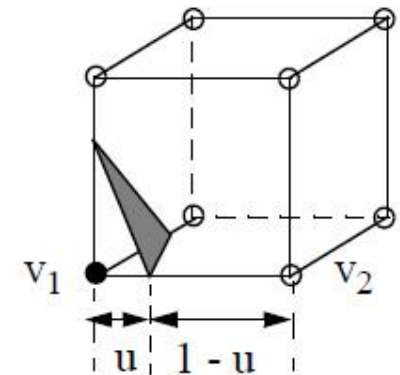


The 15 Cube Combinations

- The exact position of the polygon vertex on a cube edge is found by linear interpolation:

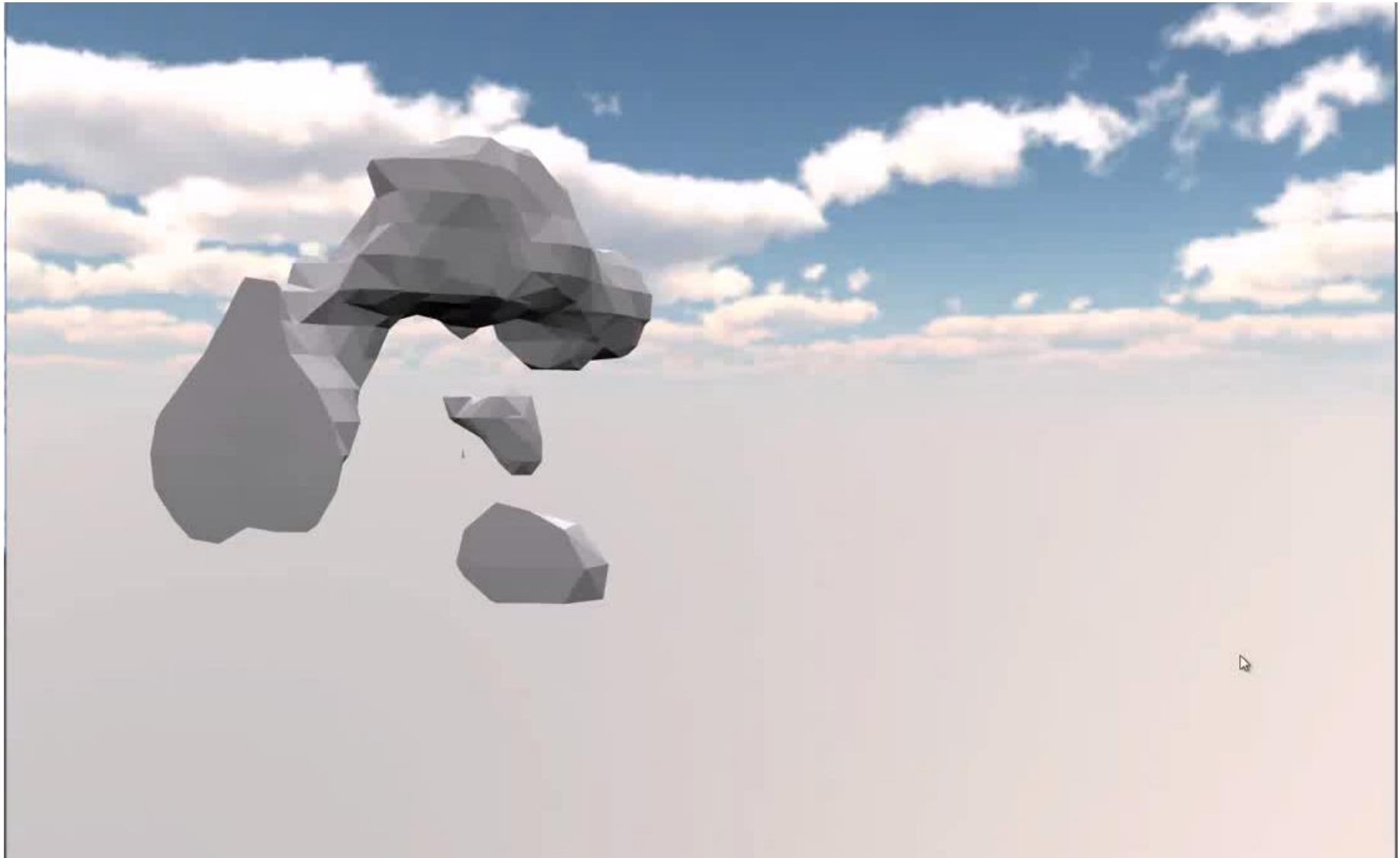
$$iso = v_1 \cdot (1 - u) + v_2 \cdot u \quad \longrightarrow \quad u = \frac{v_1 - iso}{v_1 - v_2}$$

- Now interpolate the vertex color by:  $c_1 = uc_2 + (1 - u)c_1$
- Interpolate the vertex normal by:  $n_1 = ug_2 + (1 - u)g_1$



(the  $g_1$  and  $g_2$  are the gradient vectors at  $v_1$  and  $v_2$  obtained by central differencing)

# REAL-TIME MARCHING CUBES



# WHAT IS IT?



10 petaFLOPS Titan supercomputer (released in 2012)

- $10^{15}$  floating point ops per second (1 PetaFlop)

18,688 AMD Opteron 6274 16-core CPUs

18,688 Nvidia Tesla K20X GPUs

# EVEN FASTER NOW...



Summit supercomputer (2018, #1 worldwide, Oak Ridge Nat'l Lab)

- 200 petaFLOPS (2x the top speed of TaihuLight, previous #1)
- 4,608 compute servers (each two 22-core IBM Power9 processors and six NVidia Tesla V100 GPUs)



# WHAT DOES IT DO?

Compute, compute, compute

Examples:

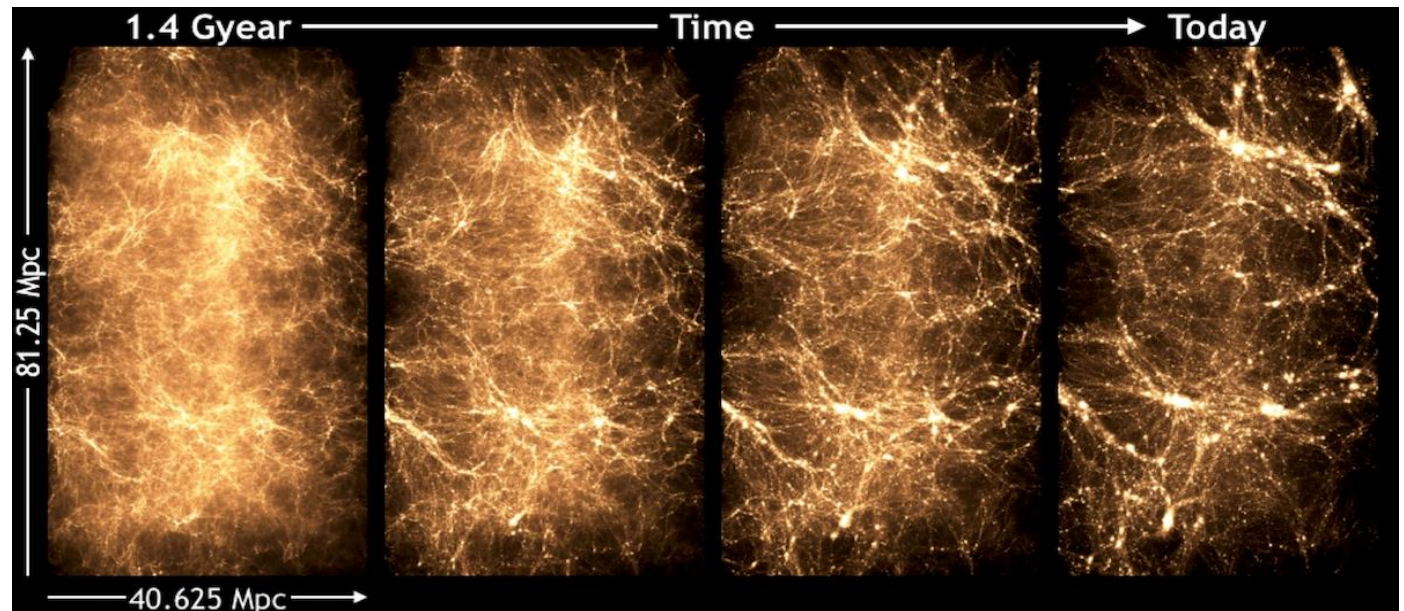
- S3D, a project that models the molecular physics of combustion, aims to improve the efficiency of diesel and biofuel engines
- Denovo simulates nuclear reactions with the aim of improving the efficiency and reducing the waste of nuclear reactors
- WL-LSMS simulates the interactions between electrons and atoms in magnetic materials at temperatures other than absolute zero
- Bonsai is simulating the Milky Way Galaxy on a star by star basis, with 200 billion stars
- Non-Equilibrium Radiation Diffusion (NRDF) plots non-charged particles through supernovae with potential applications in laser fusion, fluid dynamics, medical imaging, nuclear reactors, energy storage and combustion

# WHAT DOES IT OUTPUT

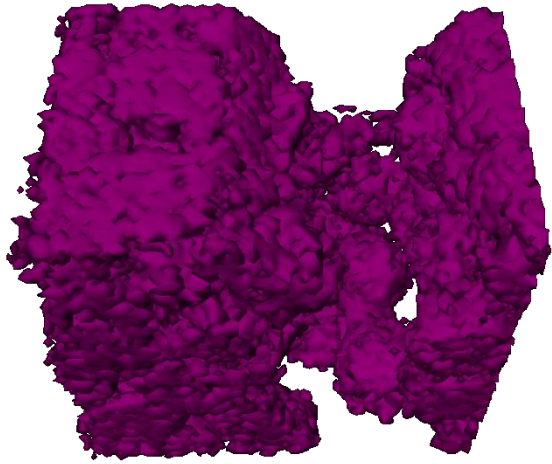
Numbers, lots of them

- Titan's I/O subsystem is capable of pushing around 240 GB/s of data
- that's a lot to visualize

Example: a visualization of the Q Continuum simulation for cosmology

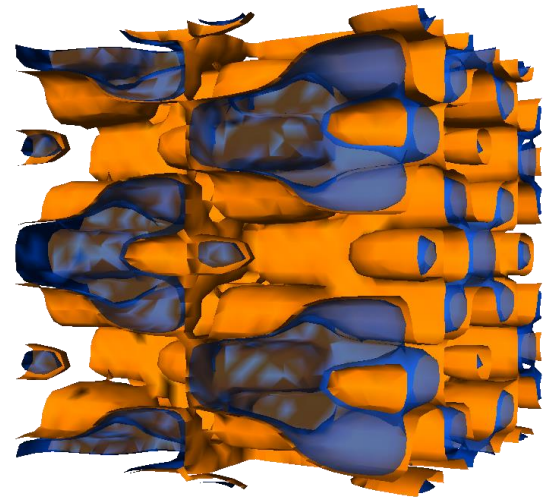
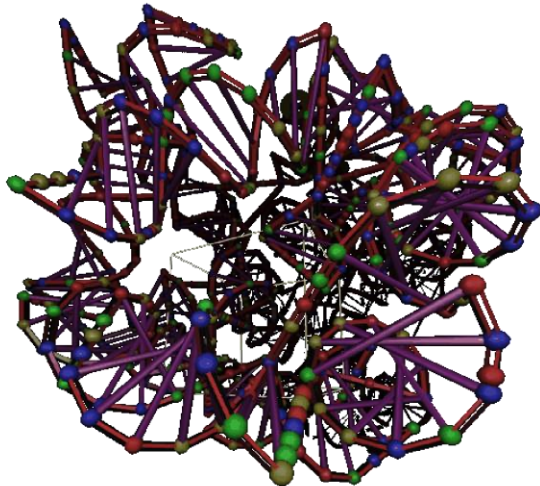


# MORE EXAMPLES



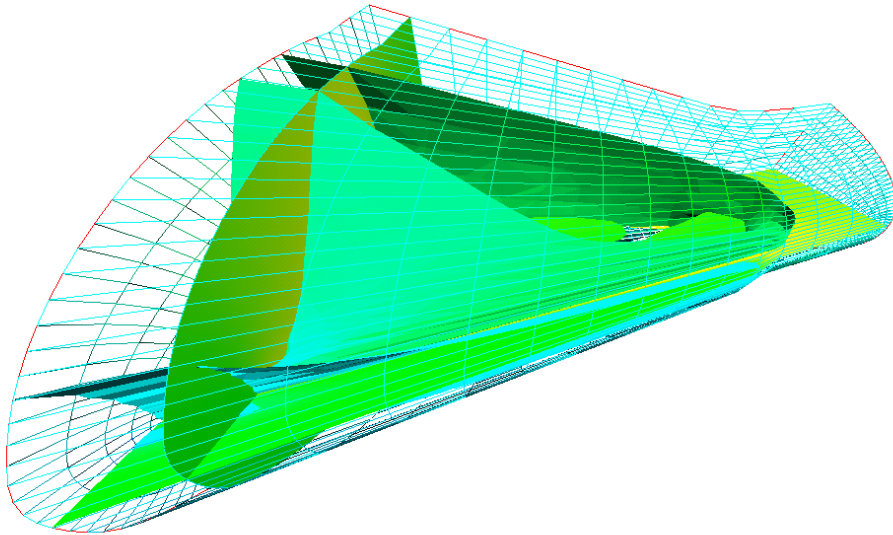
Nuclear, Quantum, and Molecular Modeling

Structures, Fluids and Fields

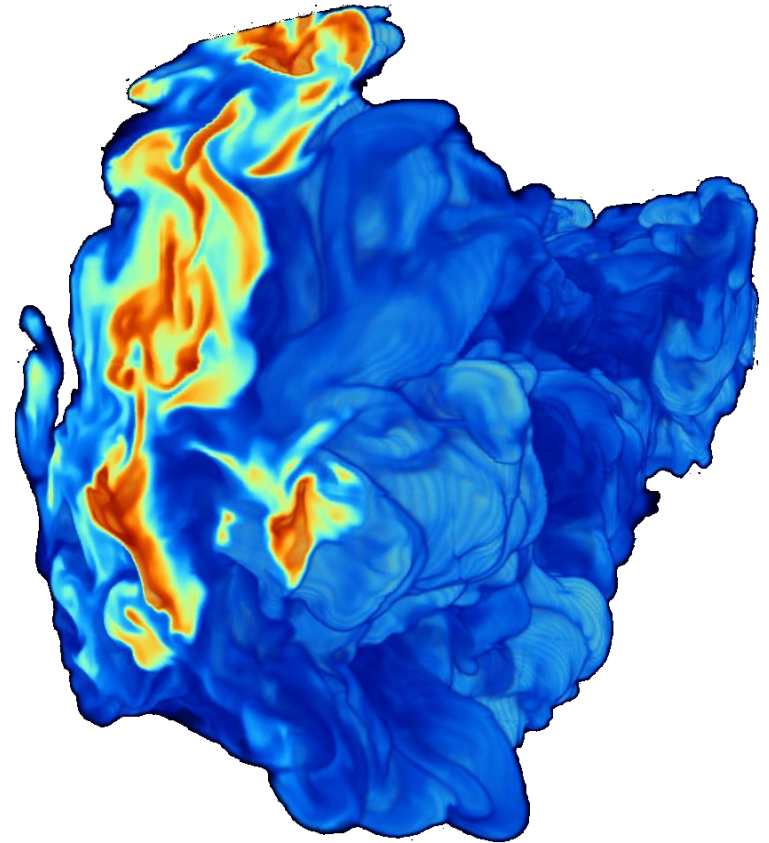


Advanced Imaging and Data Management

# MORE EXAMPLES



Surface Rendering with vTK  
(The Visualization Toolkit)



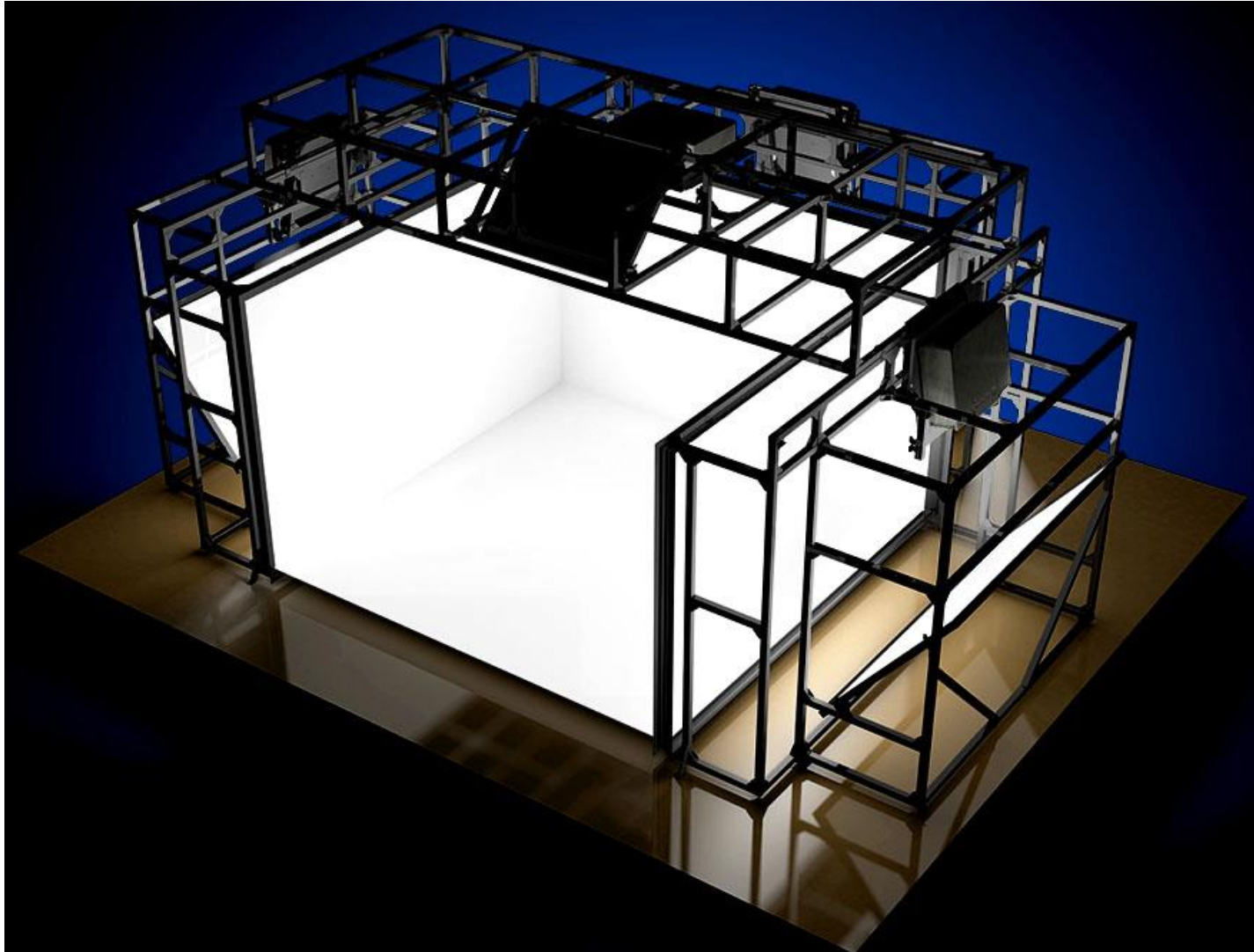
Volume Rendering

WHERE TO VISUALIZE ALL THIS?

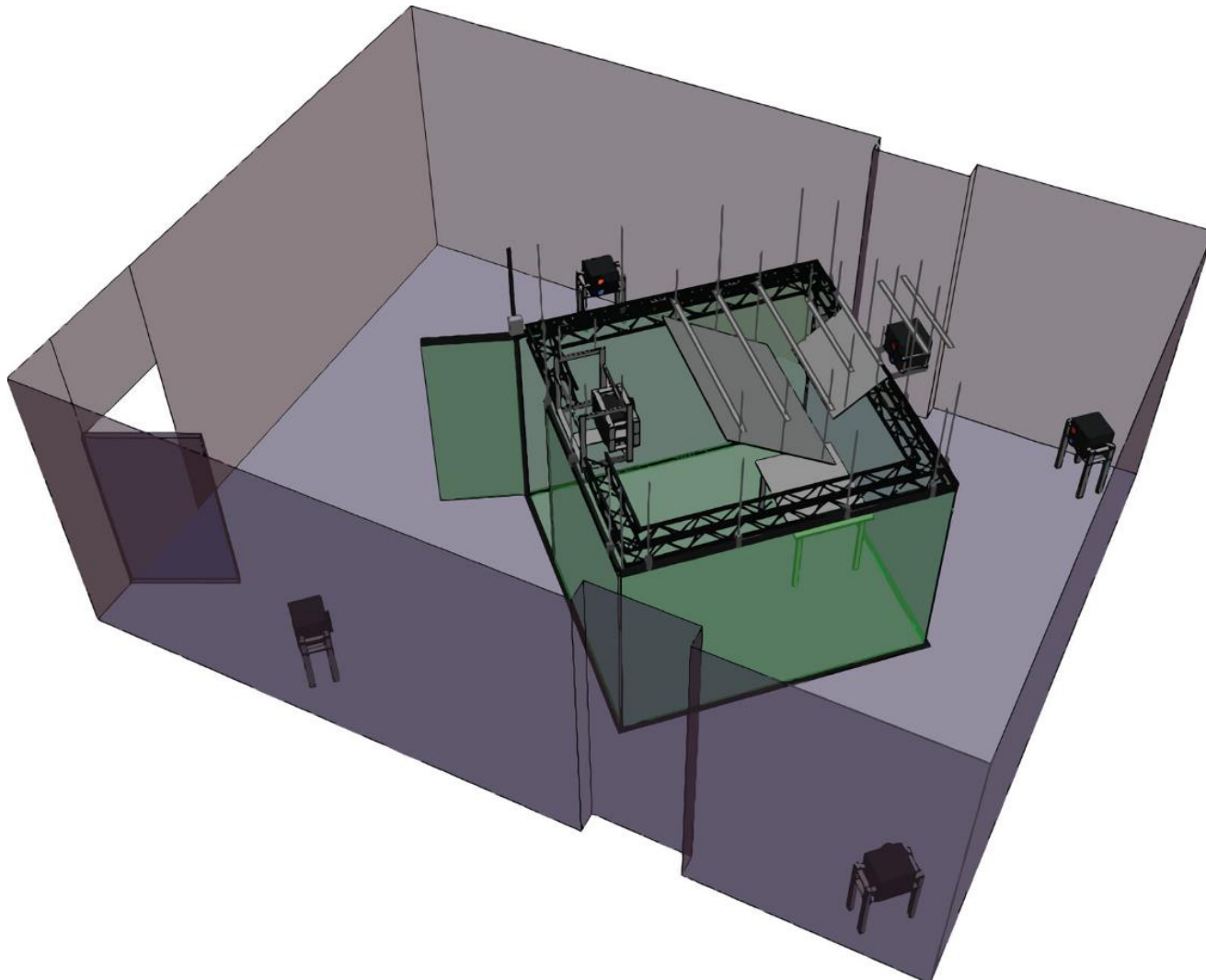
# DISPLAY WALL



# CAVE



# THE STONY BROOK IMMERSIVE CABIN

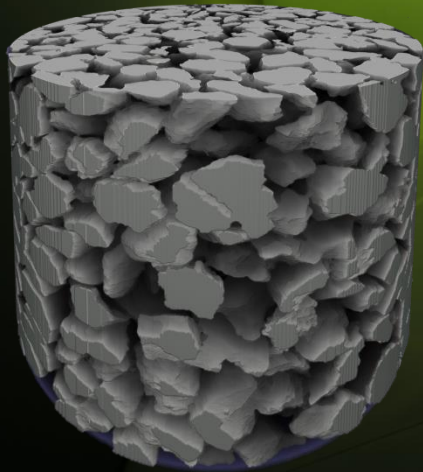




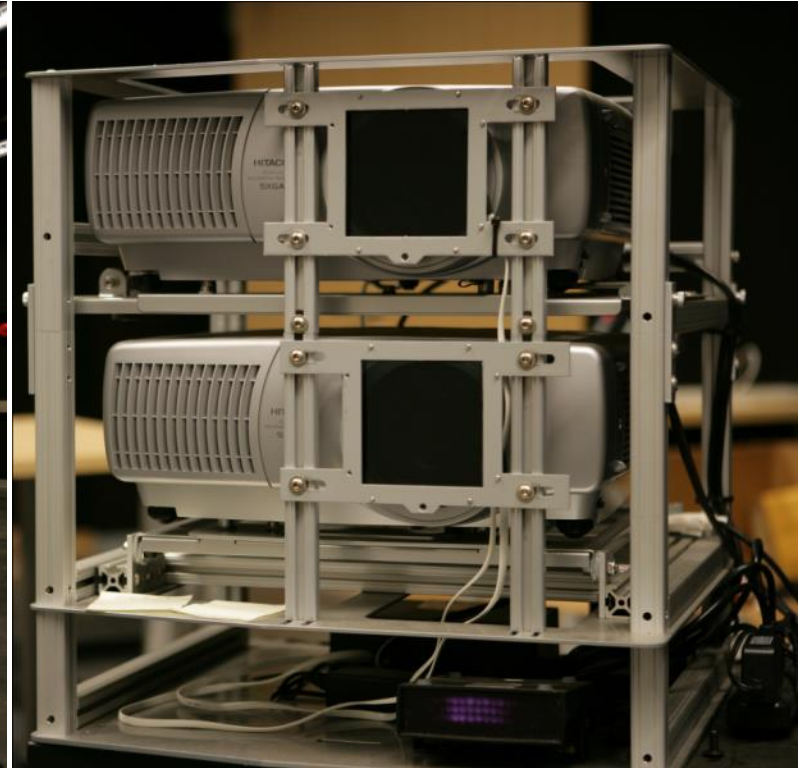
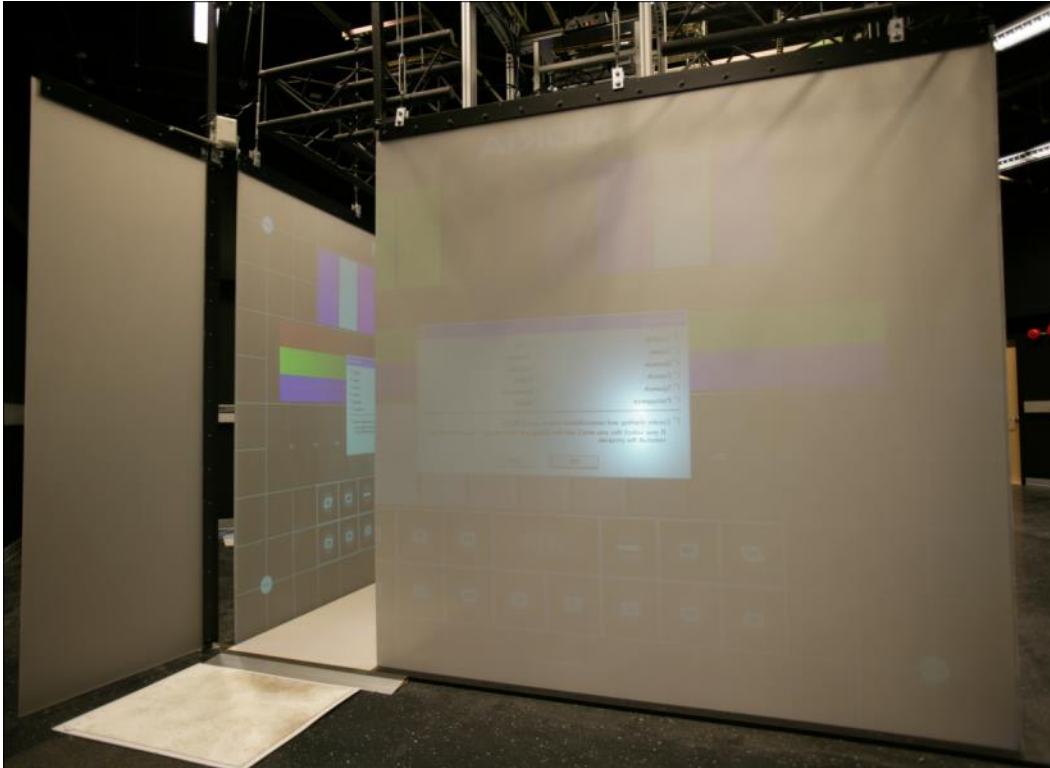
# CAVE



# Microtomography (BNL, soil sample)



# THE STONY BROOK IMMERSIVE CABIN



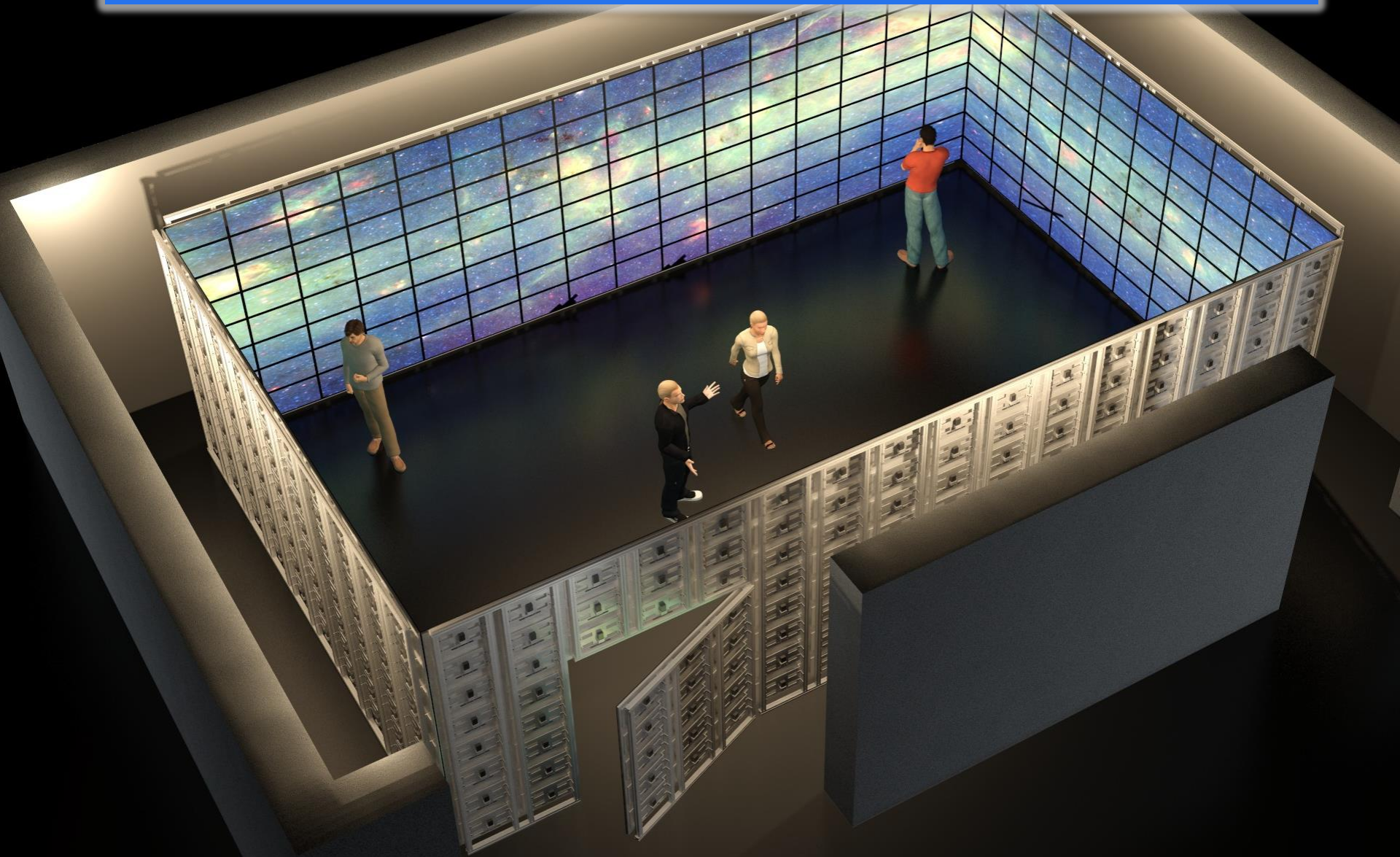
## Projector based system

- 5 walls, 12'×12' footprint, 8' tall
- difficult to scale up to Giga-pixel range

CAN WE GET BIGGER?

(yes we can)

# *The Stony Brook University Reality Deck*



# THE REALITY DECK – UNDER THE HOOD

## Visualization

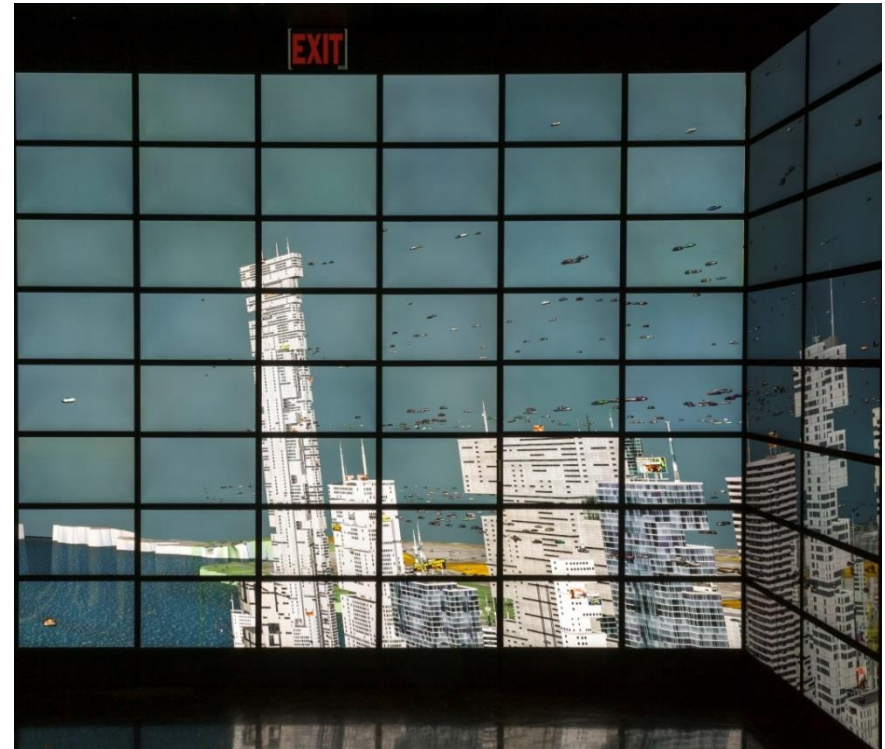
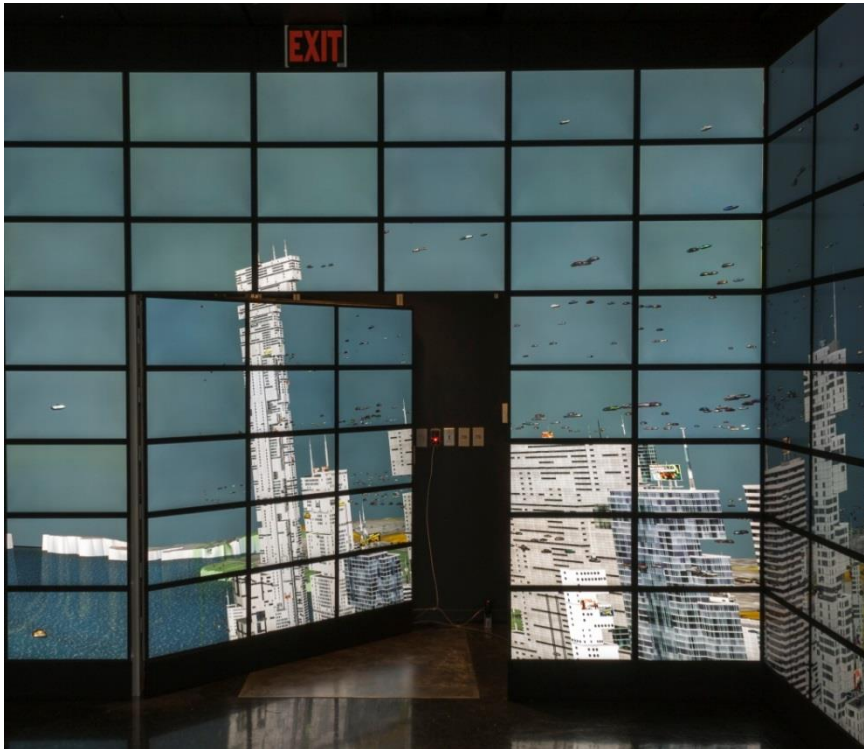
- 30'×40'×11' environment
- 416 UQXGA LCD Displays
  - 2,560×1,440 resolution over 50'-100' DisplayPort cables
  - fast response time, wide viewing angles, good dynamic range
- 20-node GPU cluster, each node equipped with:
  - 2× Six-core CPUs, 48 GB Ram
  - 4× AMD FirePro V9800 with 4GB Ram and 6 DisplayPort outputs each
  - AMD S400 hardware video synchronization card
  - 40Gb Infiniband adapter
  - 1TB storage
- In total:
  - 1,533,542,400 pixels (1.5 Gigapixel) over 6 miles of DisplayPort cables
  - 240 CPU cores: 2.3 TFLOPs peak performance, 20 TB distributed memory
  - 80 GPUs: 220 TFLOPs peak performance, 320 GB distributed memory

# AUTOMATIC DOOR

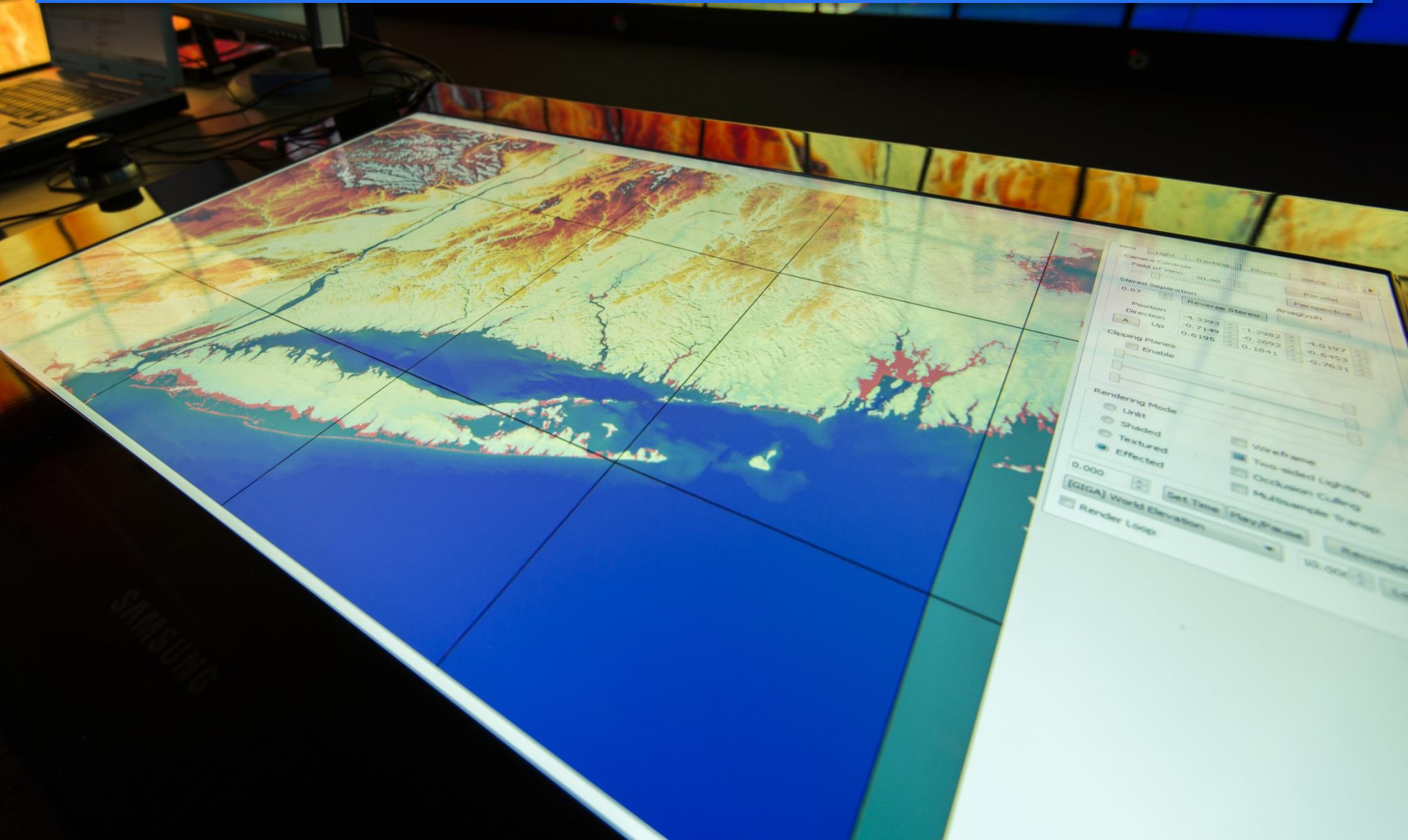
3×5 section of displays

Visually indistinguishable from rest of display

- allows for a fully enclosed visualization environment



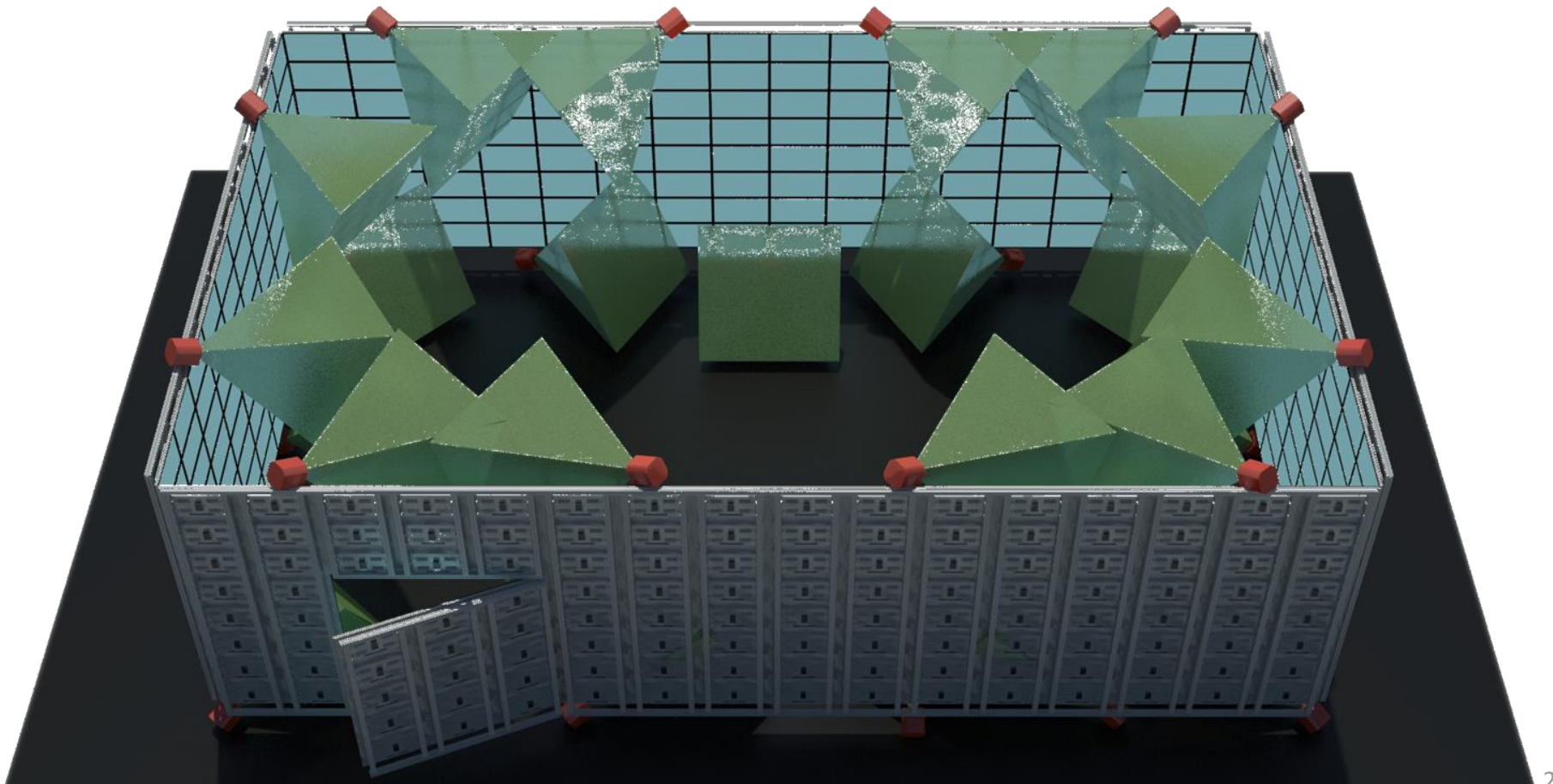
# Touch Table





# REALITY DECK TRACKING SYSTEM

24-camera infrared optical system from OptiTrack

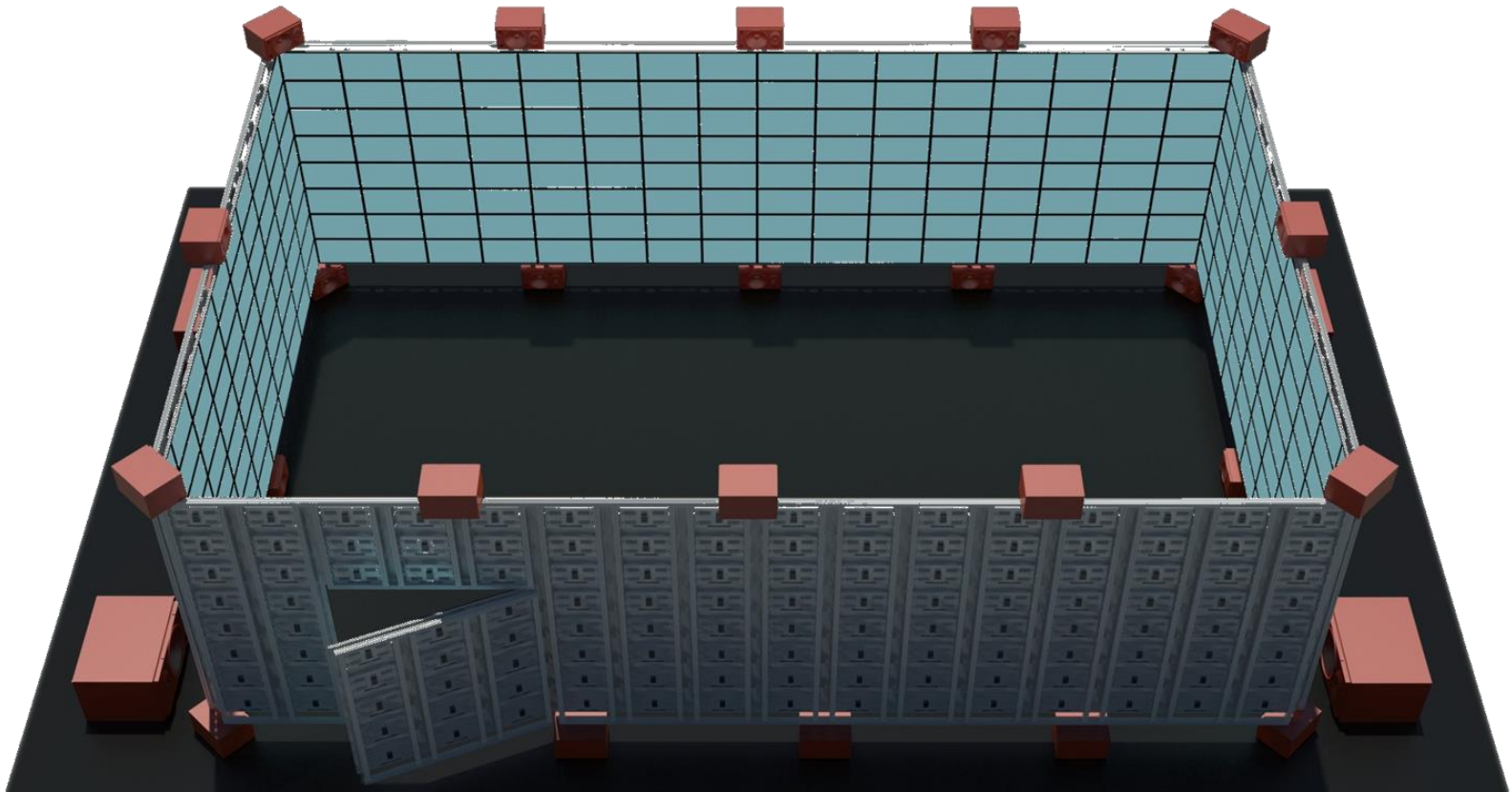


# REALITY DECK SOUND SYSTEM

24.4 channel professional-grade system

Positional audio with real-time ambisonics

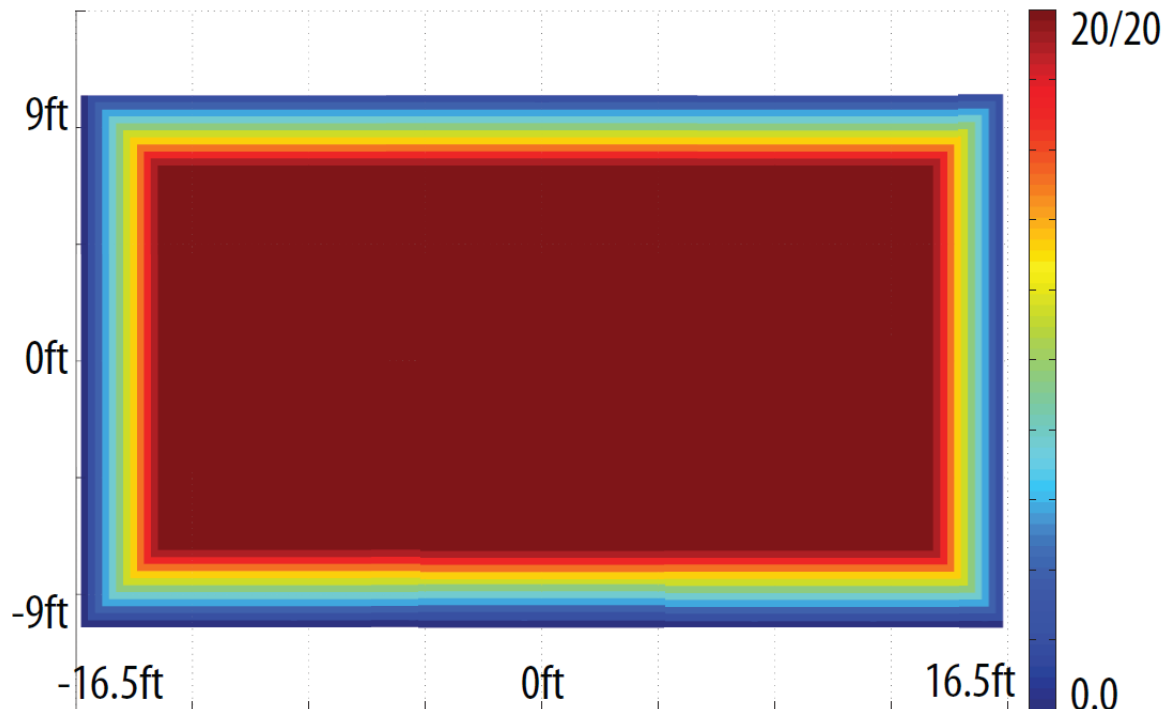
- using the Rapture3D OpenAL driver



# UNIFORMLY HIGH VISUAL ACUITY

User can make visual queries at an instant

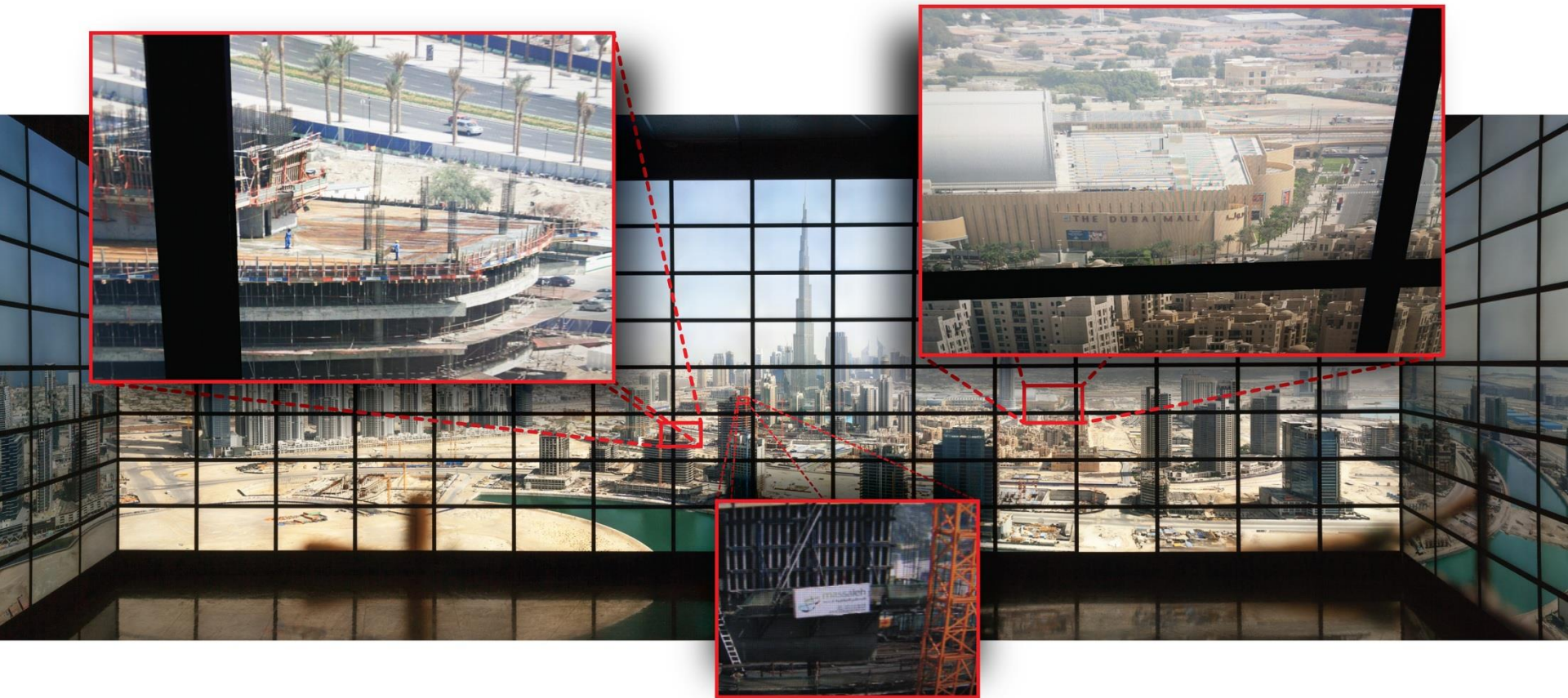
- walk up to obtain more detail
- just like in real life – hence the Realty Deck
- 20/20 visual acuity at 1.5'-2' away



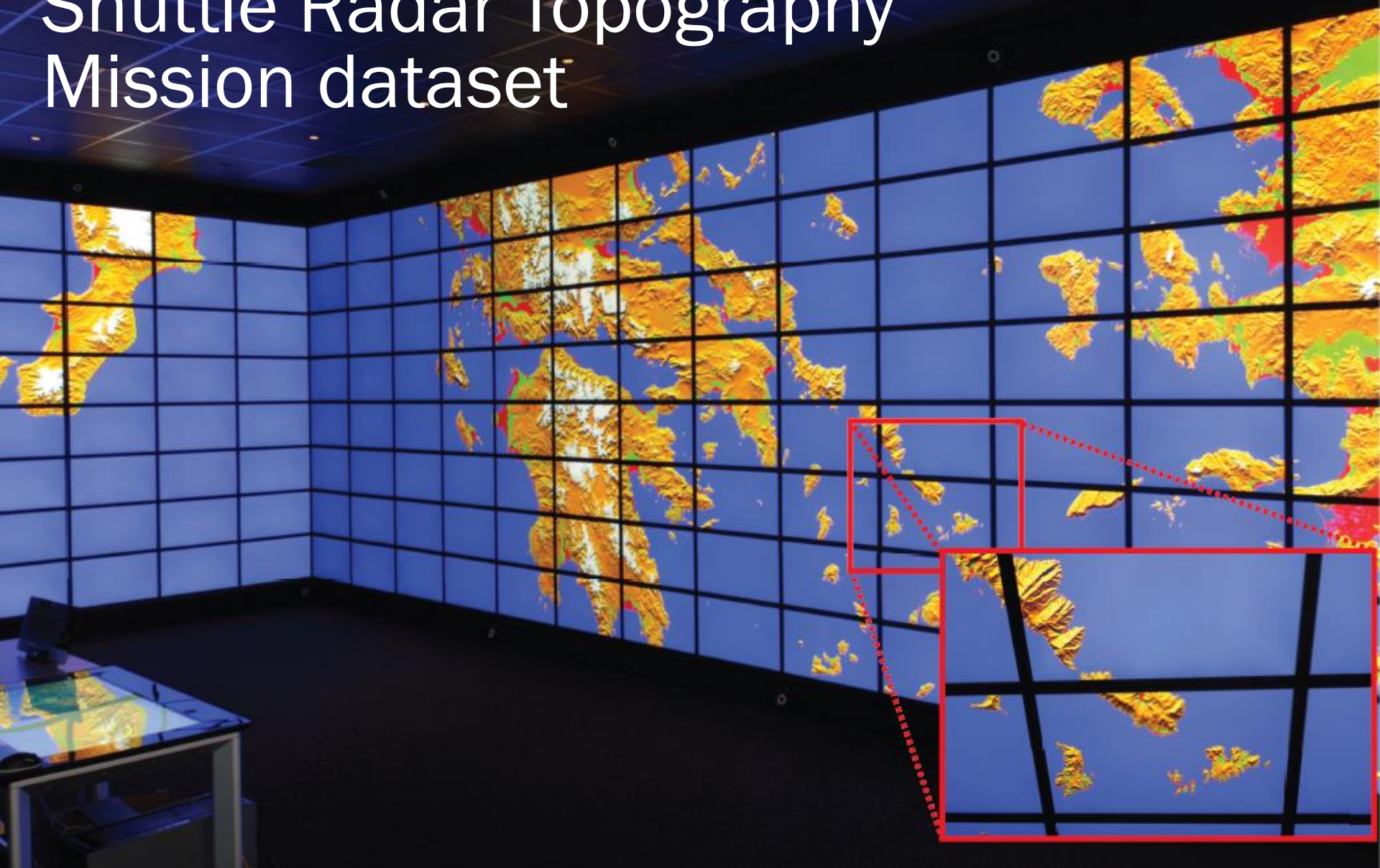
# GIGAPIXEL VISUALIZATION

## Dubai dataset

- 45 Gigapixels, 180° field of view



# Shuttle Radar Topography Mission dataset



# Terrain Modeling



# 3D Relief Map

*Sea level simulation*







# Protein Visualization *Reality Deck*



# SCIENTIFIC SIMULATION

Say, you want to simulate the airflow around an airplane wing

- where is the flow most interesting?

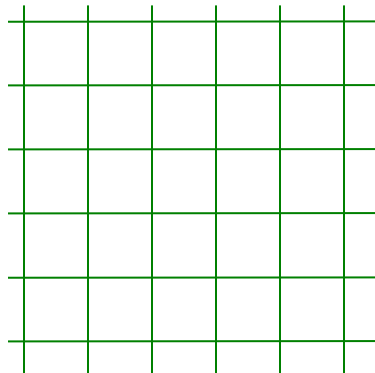
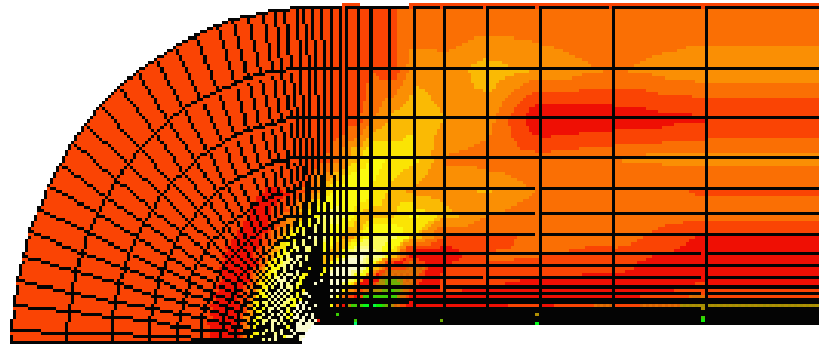


- right, close to the surface

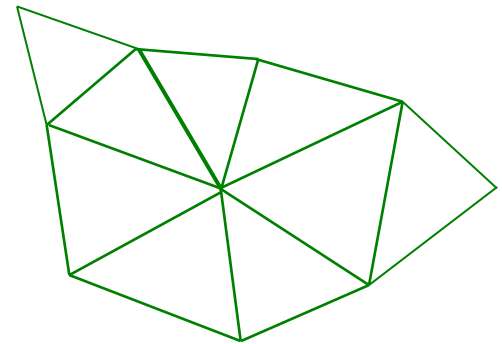


# SIMULATION LATTICE

Make the simulation lattice densest along the surface



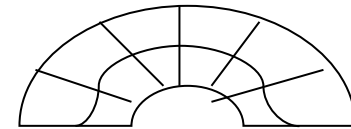
Regular → irregular grids



# GRIDS

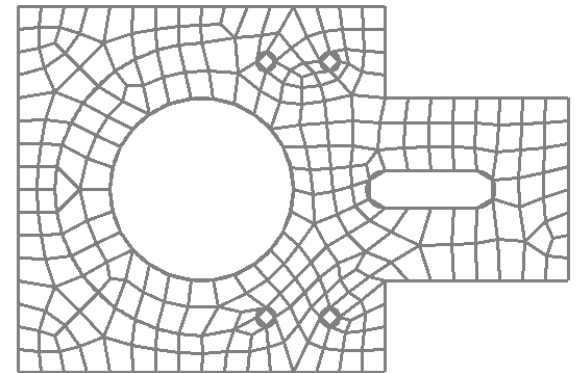
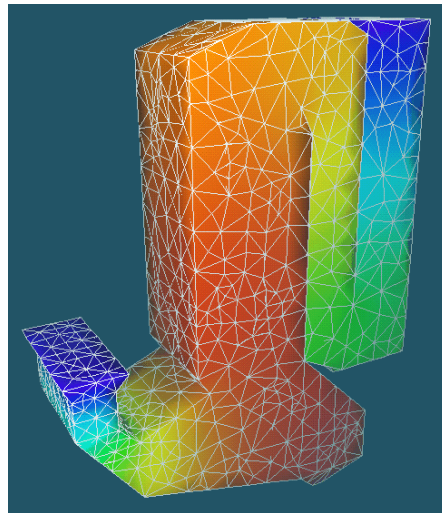
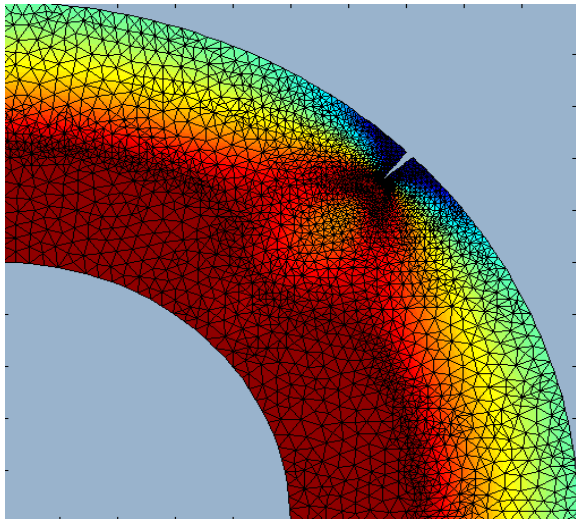
## Structured grid

- more or less a bent regular grid



## Unstructured grid

- collection of vertices, edges, faces and cells whose connectivity information must be explicitly stored

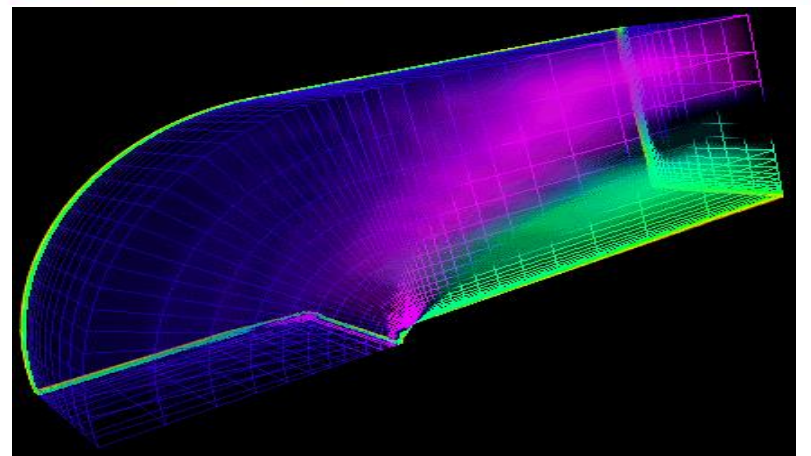
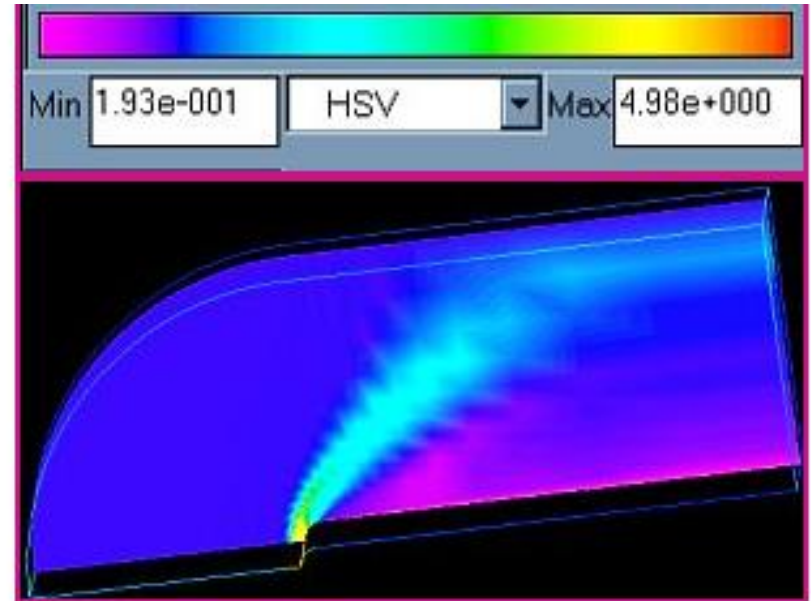
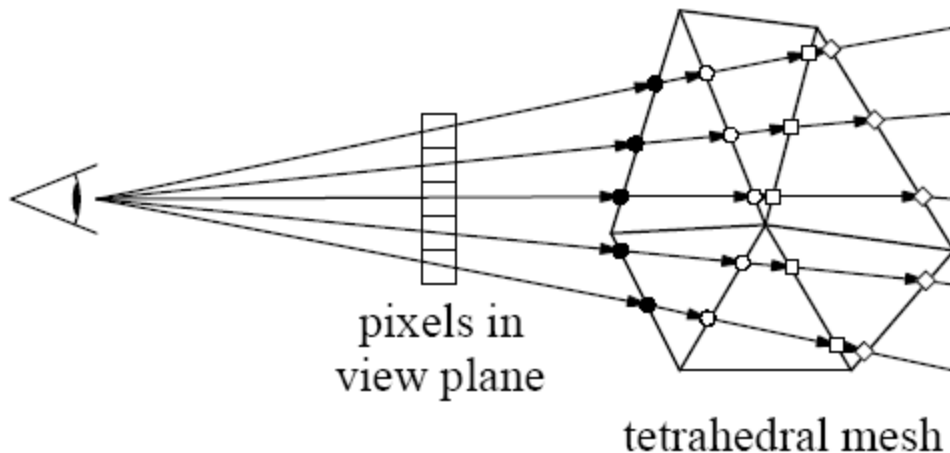


# THE BLUNTFIN DATASET

Mapping flow strength to color

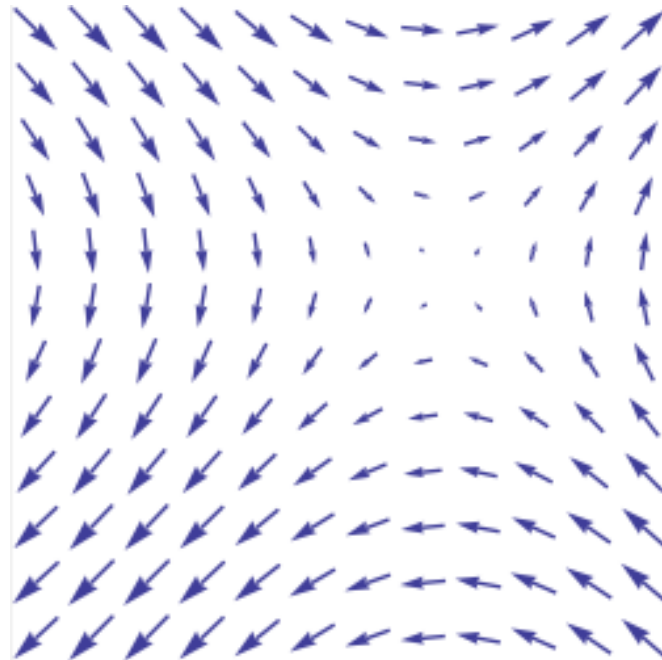
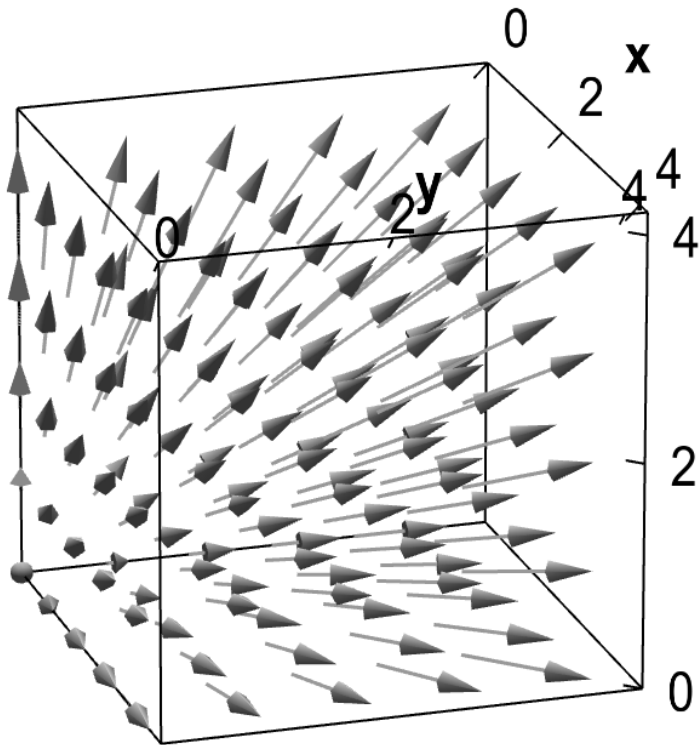
Rendering by cell traversal

- go from cell to cell
- composite colors and opacities



# FLOW VISUALIZATION

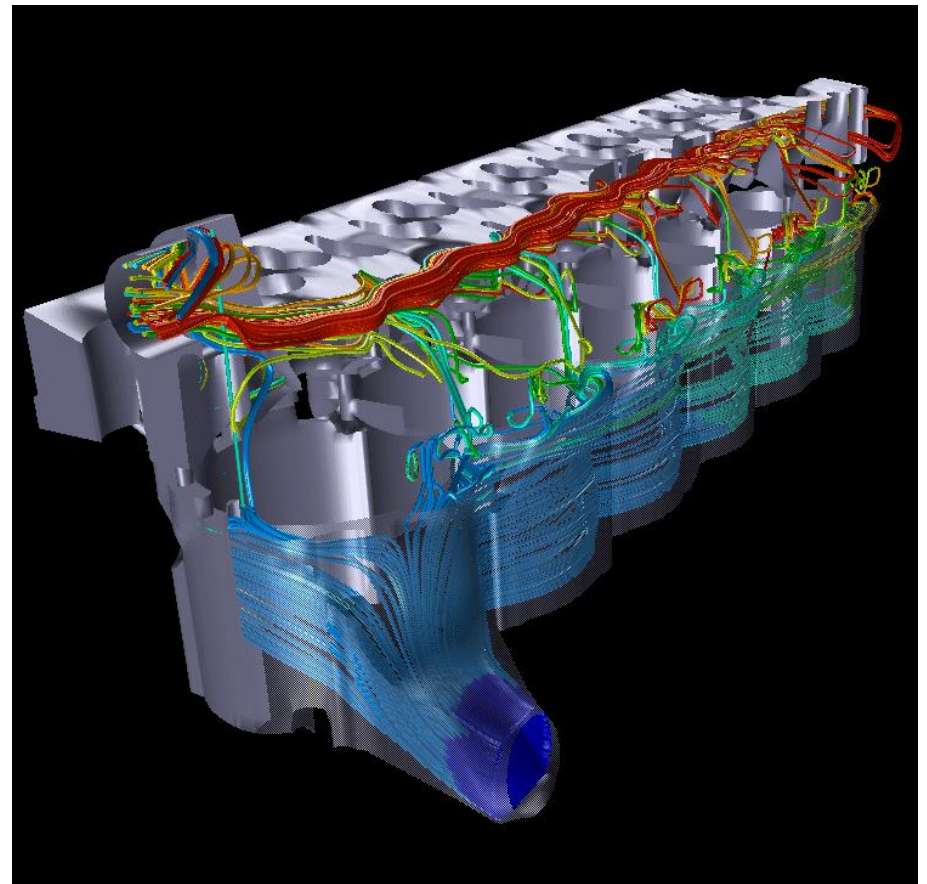
Also called vector field visualization



# STREAM LINES

Perform an integration through the vector field

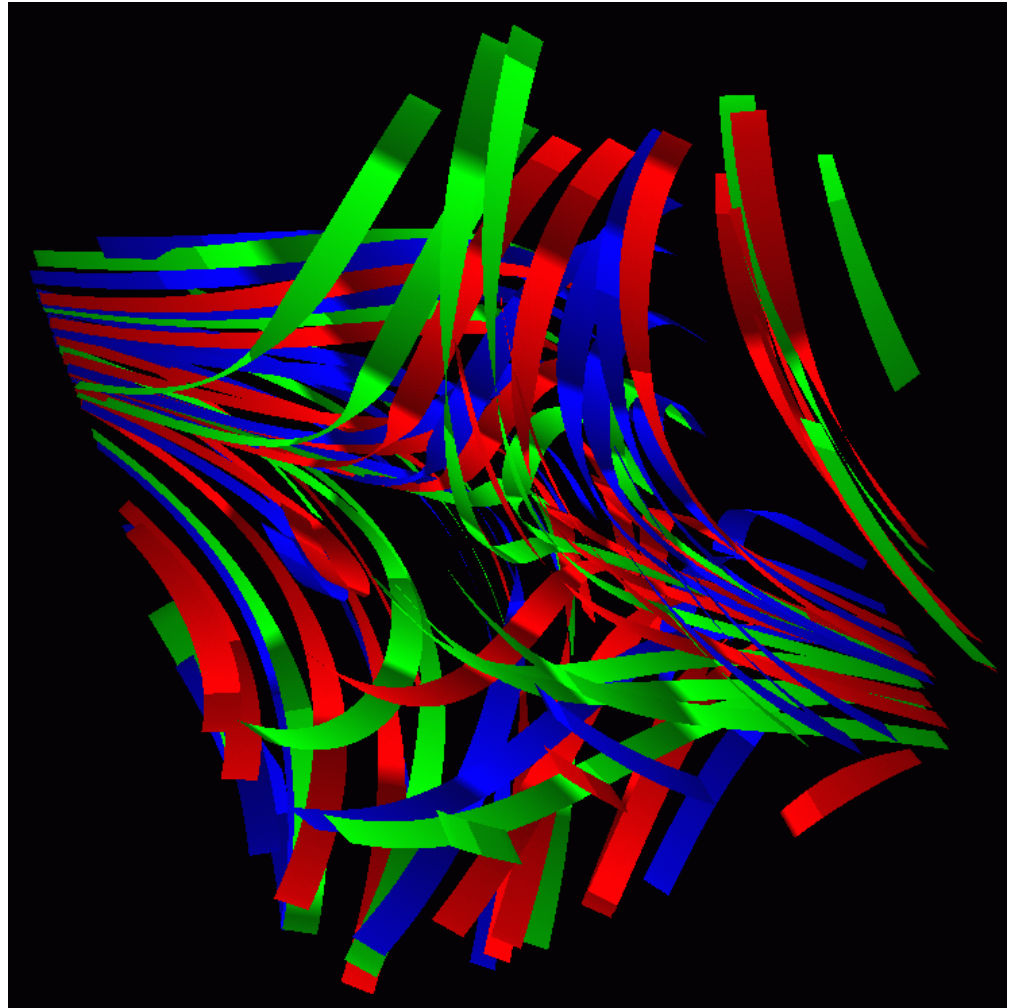
- color maps to temperature



# STREAM RIBBONS

## Connect two streamlines

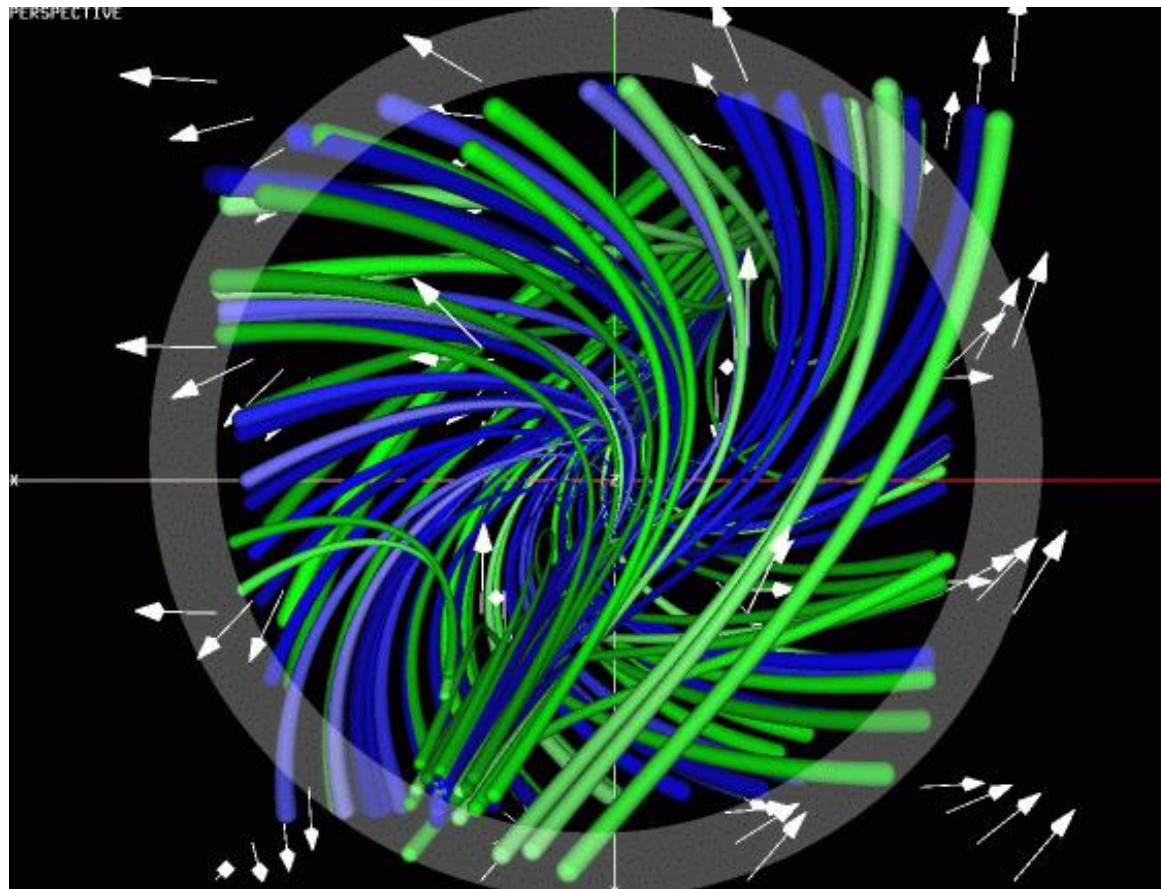
- the center streamline gives direction, the other two indicate the twisting





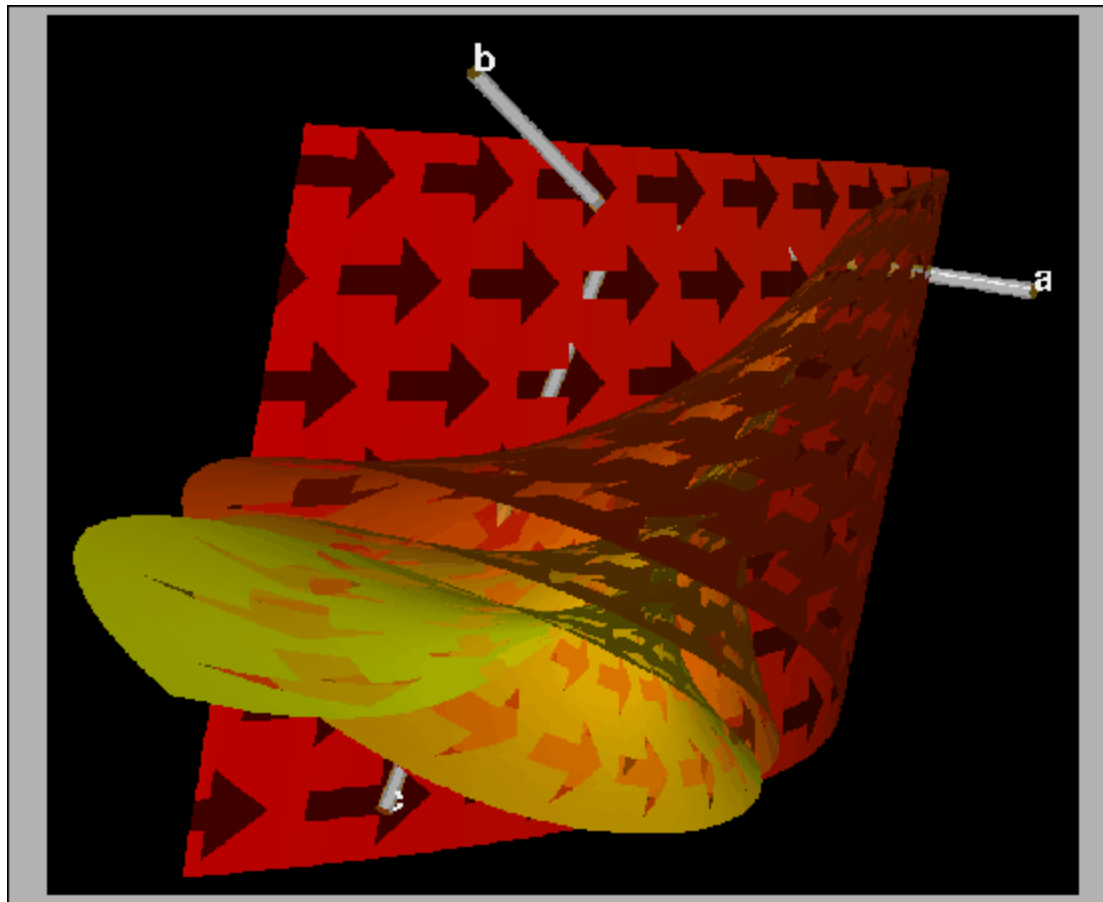
# STREAM TUBES

Connect three or more streamlines



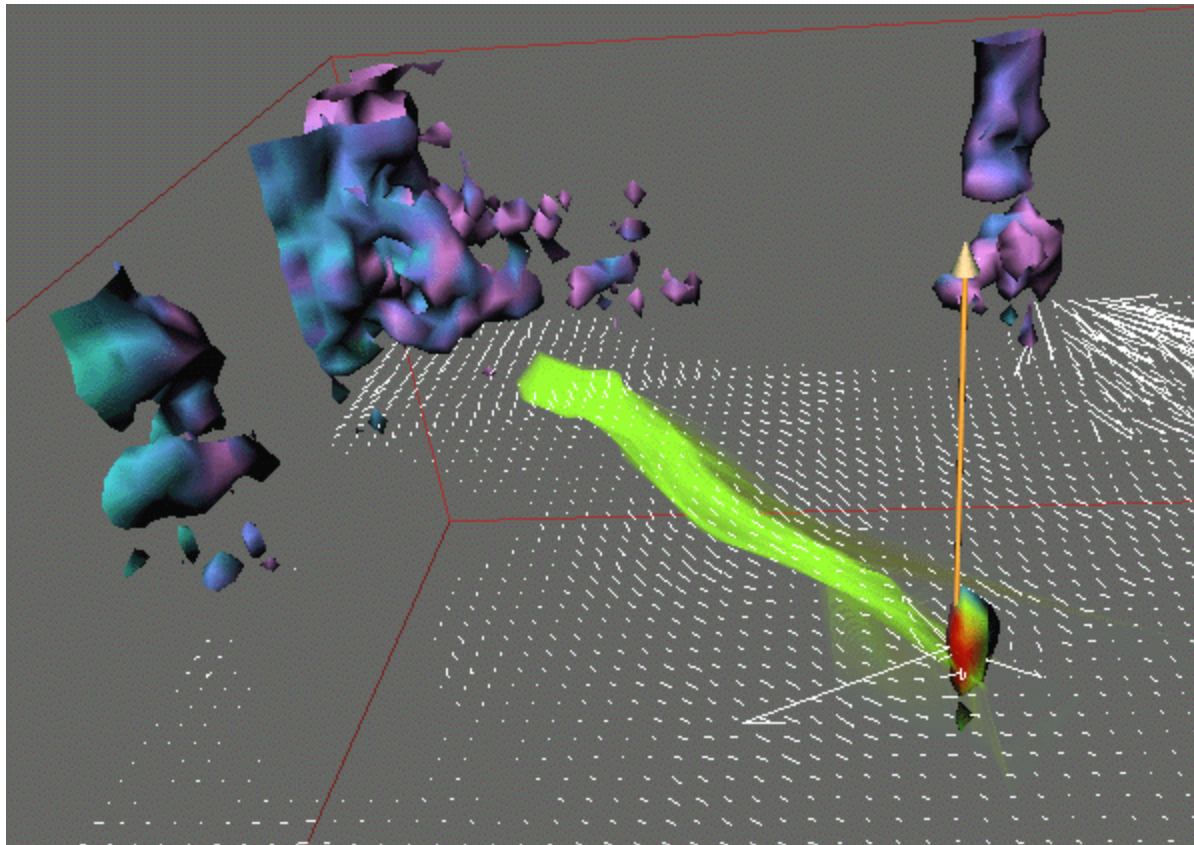
# STREAM SURFACES

Sweep a line segment through the vector field



# STREAM BALLS

Smoke is injected into the flow field and compresses/expands due to the vector field



# GLOBAL TECHNIQUES

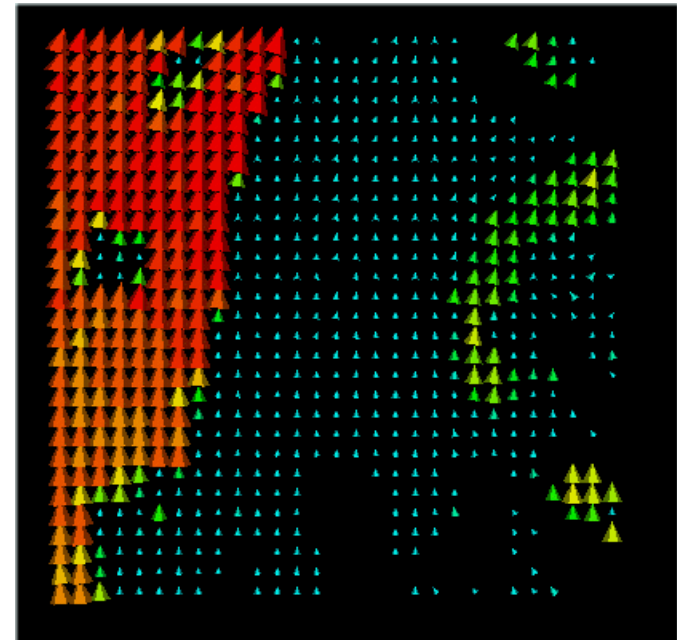
Seek to give a more global view of the vector field

## Hedgehogs

- oriented lines spread over the volume, indicating the orientation and magnitude of the flow
- do not show directional information

## Glyphs, arrows

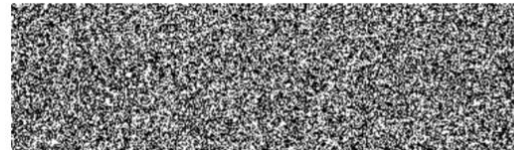
- icons that show directions, but tend to clutter the display



# LINE INTEGRAL CONVOLUTION (LIC)

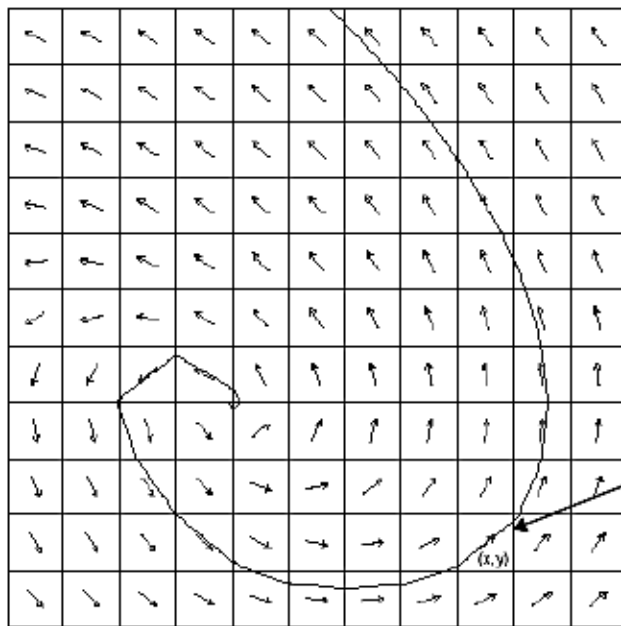
- Input:

- a 2D vector field

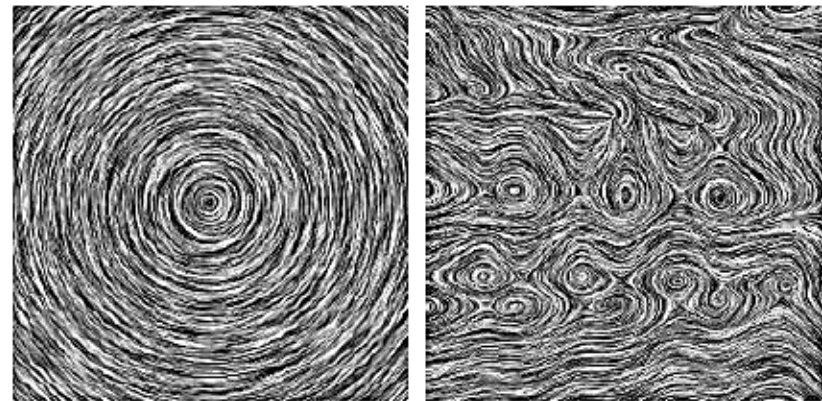


salt+pepper noise

- an image that will be “smeared” according to the stream lines described by the vector field



input vector field



output image = line-integrated white noise image

stream line

For each output pixel  $(x, y)$

Follow the stream line forward for some distance  $\Delta s$

Multiply each pixel value by a 1D filter kernel and add

Follow the stream line backward for some distance  $\Delta s$

Multiply each pixel value by a 1D filter kernel and add

Follow the stream line backward for some distance  $D_s$

filter aligned with the stream line



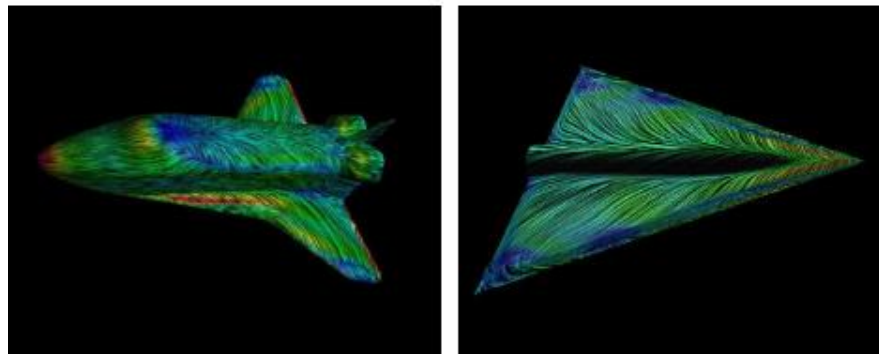
# LINE INTEGRAL CONVOLUTION (LIC)



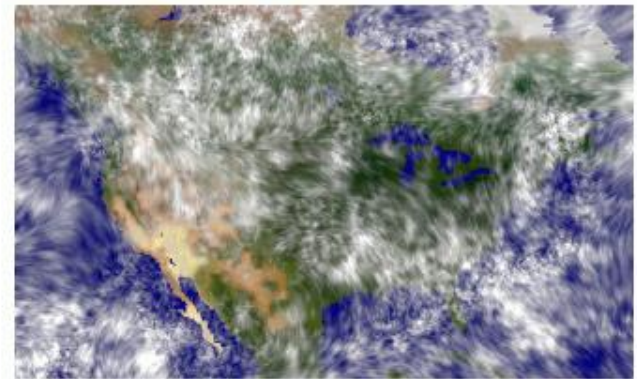
a flower image with different vector fields



a simple motion vector field over the hand



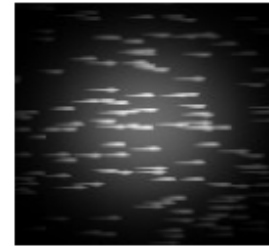
mapping LIC onto an object surface



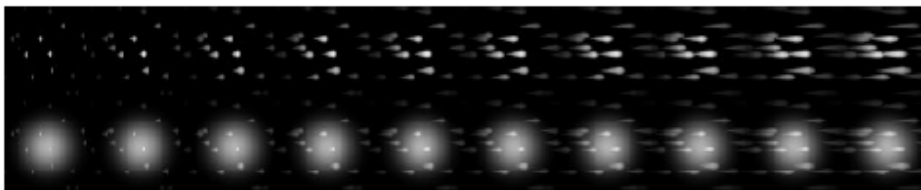
using vector magnitude to determine  $\Delta s$

# TEXTURED SPLATS

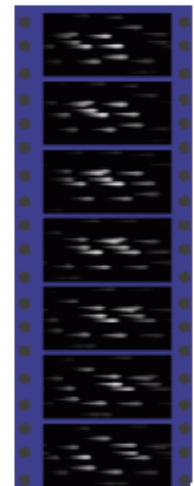
- Embed flow field vector icons into a splat
  - this enables smooth blending of neighboring icons



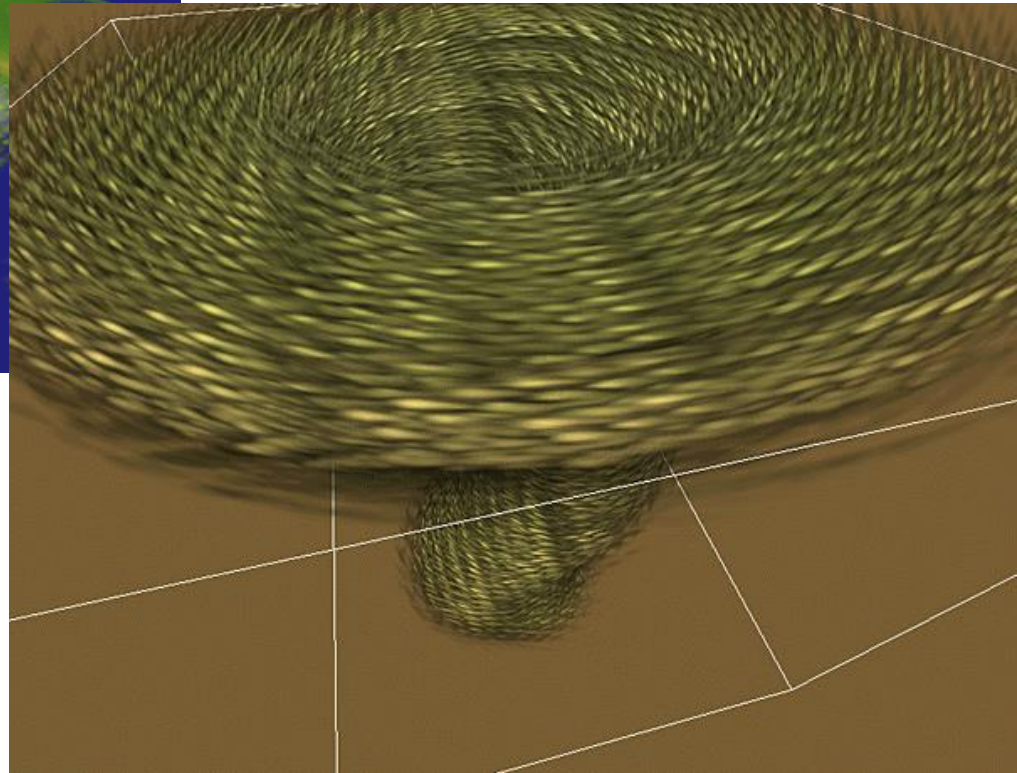
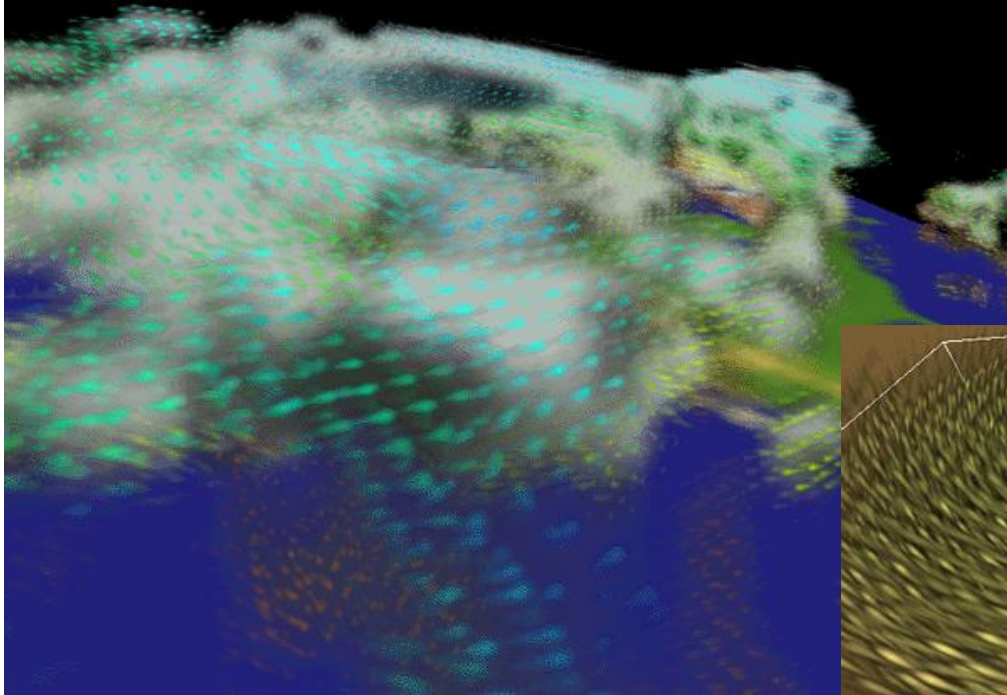
- Create a table of texture splats with varying icon distribution (to prevent regular patterns)
- For a given location, select a random splat and rotate corresponding to the flow field direction
- Since the flow field is 3D, the component of the vectors that is parallel to the screen varies
- Need to provide splats that accommodate for vector foreshortening when the flow heads towards us



- Animated display
  - store a splat table with vector icons that are cyclically shifted from left to right
  - cycle through this table when picking splats to update the animated display



# TEXTURED SPLATS EXAMPLES





# POPULAR SOFTWARE & LIBRARIES

## VTK

- The Visualization Toolkit library
- developed by Kitware

## Paraview

- built on top of VTK
- open-source
- multi-platform
- developed by Sandia & Los Alamos National Labs

## VisIt

- open source
- developed by Lawrence Livermore National Lab

